



KNX S1R-UP Multifunctional Actuators

Technical specifications and installation instructions

Item numbers 70511 (KNX S1R-UP), 70512 (KNX S1R-BA2-UP), 70513 (KNX S1R-BA4-UP)









1. Description

Actuators KNX S1R-UP with integrated façade control have a multifunctional output which can connect to either a drive with Up/Down control (blinds, awnings, shutters, windows) or two switchable devices (On/Off for light and ventilation). Because the output is designed to be free of potential, other systems can also be controlled, e.g. via the manual switch input on a motor control unit.

Automation can be specified externally or internally. Internally, there are numerous options available for blocking, locking (e.g. master-slave) and priority definitions (e.g. manual-automatic). Scenes can be saved and called up via the bus (scene control with 16 scenes per drive).

The KNX S1R-B4-UP and KNX S1R-BA2-UP models are equipped with inputs which are used as bus inputs (buttons, alarms, etc.) or for T-NTC temperature sensors. The KNX S1R-UP model does not have any analogue/digital inputs.

Functions:

- Free of potential multifunctional output for a 230 V drive (shading, windows) or connection of two switchable devices (light, fan)
- Relays switch with low wear near the zero-voltage transition
- Inputs for binary contact or temperature sensor (not on KNX S1R-UP)
- Automatic runtime measurement of the drives for positioning (incl. fault reporting object)
- Position feedback (movement position, also slat position for shutters)
- **Position storage** (movement position) via 1-bit object (storage and call-up e.g. via buttons)
- Parameters for taking drive and mechanics **downtimes** into account
- Control via internal or external automation functions
- Integrated shade control with slat adjustment for shutters based on the position of the sun
- Scene control for movement position with 16 scenes per drive (also slat position for shutters)
- Mutual locking of two drives using zero position sensors prevents collisions e.g. of shade and window (master-slave)
- Blocking objects and alarm reports have different priorities, so safety functions always
- take precedence (e.g. wind block)Manual or automatic **priority** setting via time or communication object
- 4 temperature switching outputs in the application program with adjustable threshold
- values (presetting the parameters or communication object)

 Brief time limit (movement command blocked) and 2 movement limits

Configuration is made using the KNX software ETS 5. The **product file** can be downloaded from the ETS online catalogue and the Elsner Elektronik website on **www.elsner-elektronik.de** in the "Service" menu.

1.0.1. Scope of delivery

Actuator

1.1. Technical specification

Housing	Plastic
Colour	White
Assembly	Flush-mounted (in connector socket Ø 60 mm, 60 mm deep)
Protection category	IP 20
Dimensions	approx. $50 \times 50 \times 54 (W \times H \times D, mm)$
Weight	approx. 100 g
Ambient temperature	Operation -20+45°C, storage -30+85°C
Ambient humidity	580% RH, non-condensing
Operating voltage	KNX bus voltage
Current at the bus	10 mA
Output	1 × output, free of potential with 2 connections for drive up/down or 2 devices (power supply, PE/N/1/2). Secured by a microfuse T4.0 A. Can withstand a total of max. 4 A (resistive load), switch-on current totally max. 4 A at ≤ 20ms.
Maximum load	Each terminal contact may be loaded with a maximum of 10 A.
Minimum current for runt- ime measurement	AC effektive 200 mA
Inputs	KNX S1R-UP: no inputs KNX S1R-BA2-UP: 2× analogue/digital. KNX S1R-BA4-UP: 4× analogue/digital. max. output length 10 m
Setting range for the T-NTC temperature sensor on the input	-30°C+80°C
Data output	KNX +/- bus connector terminal
BCU type	Integrated microcontroller
PEI type	0
Group addresses	max. 1024

Assignments	max. 1024
Communication objects	KNX S1R-UP: 147
	KNX S1R-BA2-UP: 174
	KNX S1R-BA4-UP: 200

The product is compliant with the provisions of EU guidelines.

2. Installation and start-up

2.1. Installation notes



Installation, testing, operational start-up and troubleshooting should only be performed by an electrician.

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DANGER!

Risk to life from live voltage (mains voltage)!

There are unprotected live components within the device.

- VDE regulations and national regulations are to be followed.
- Ensure that all lines to be assembled are free of voltage and take precautions against accidental switching on.
- Do not use the device if it is damaged.
- Take the device or system out of service and secure it against unintentional use, if it can be assumed, that risk-free operation is no longer guaranteed.

The device is only to be used for the intended purpose described in this manual. Any improper modification or failure to follow the operating instructions voids any and all warranty and guarantee claims.

After unpacking the device, check it immediately for possible mechanical damage. If it has been damaged in transport, inform the supplier immediately.

The device may only be used as a fixed-site installation; that means only when assembled and after conclusion of all installation and operational start-up tasks and only in the surroundings designated for it.

Elsner Elektronik is not liable for any changes in norms and standards which may occur after publication of these operating instructions.

2.2. Safety notice for automatic functions

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WARNING!

Risk of injury from automatically moving components!

Parts of the system can be started by the automatic controls and be a danger to persons.

- No persons may remain in the travelling range of parts driven by an electric motor.
- Adhere to the relevant building regulations.
- Ensure that the return path/access to the building is not blocked if spending time outside the building (danger of being locked out).
- Correctly decommission the system for maintenance and cleaning work.

If there is a power outage, the system does not work. Therefore, shadings should be moved to a save position if there are anticipated weather conditions, for example, if this has not already been done by the automatic function (product protection).

If the power supply is removed, the connected drive switches off. When the power is restored, the consumer remains switched off until a new movement command is received by the actuator.

2.3. Installation

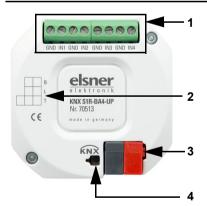


Fig. 1: Bus side

- Analogue/digital inputs connector (not for KNX S1R-UP)
- 2 Label field
- 3 KNX terminal +/-
- 4 Programming LED and programming button (countersunk)

Analogue/digital inputs connector assignment:

KNX S1R-UP: Not assigned!

KNX S1R-B2A-UP: 1: GND | 2: IN1 | 3: GND | 4: IN2

KNX S1R-BA4-UP: 1: GND | 2: IN1 | 3: GND | 4: IN2 | 5: GND | 6: IN3 | 7: GND | 8: IN4 All GND connectors are internally bridged.



Fig. 2: Output side

 Connector for drive/consumers (free of potential)

2.4. Connection

The **Actuators KNX S1R-UP** are installed in a flush-mounted socket. The connection is made using a KNX connector on the KNX data bus. In addition, a power supply for the connected drive or consumer is necessary (output free of potential).



Follow the guidelines and standards for SELV electric circuits while installing and cable laying of the KNX connection and inputs!





ATTENTION!

Relays may be switched on when starting the device for the first time!

The bistable relays used in this product may switch on in case of shock,

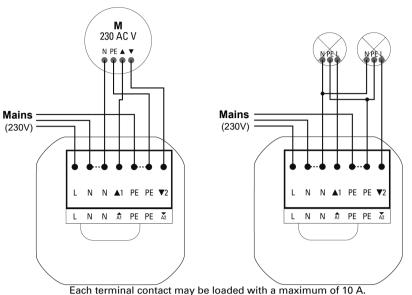
- e. g. during transportation.
- First apply the bus voltage, as this will switch off the relays. Then switch on the voltage supply of the drive.

The physical address is assigned by the KNX software. There is a button with a control LED for this on the actuator.

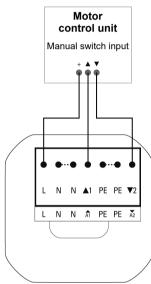
2.4.1. Connection examples

230V drive at the output:

Two 230V consumers at the output:

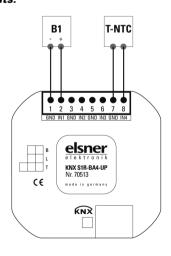


Control of an external motor control unit via the output:



Note: The Actuators KNX S1R-UP can also be used with direct-current voltage (12 V DC, 24 V DC) due to their potentialfree output. The "L" connector is used as "Com" in this case. The automatic runtime measurement is not possible with directcurrant voltage!

Inputs:



Example KNX S1R-B4-UP with binary contact on input 1 and T-NTC temperature sensor on input 4.

Connection of the temperature sensor is independent of the polarity.

2.5. Instructions for assembly and operational start-up.

Never expose actuators to water (e.g. rain) or dust. This can damage the electronics. You must not exceed a relative air humidity of 80%. Avoid condensation.

After the auxiliary voltage has been applied, the device will enter an initialisation phase lasting a few seconds. During this phase no information can be received or sent via the bus.

For KNX devices with safety functions (e.g. wind or rain blocks), it is important to set up periodical monitoring of the safety objects. The optimal ratio is 1:3 (example: if the weather station sends a value every 5 minutes, the actuator must be configured for a monitoring period of 15 minutes).

Addressing of the device at the bus 3.

The device is supplied with the bus address 15.15.255. You can program another address into the ETS by overwriting the 15.15.255 address or by teaching via the programming button.

4. Disposal

After use, the device must be disposed of or recycled in accordance with the legal regulations. Do not dispose of it with the household waste!